### Abstract

This paper presents a new sparse representation for acoustic signals based on a mixing model defined in the complex-spectrum domain (where additivity holds):

$$F_{k,t} = \sum_{i=1}^{I} H_k^{(i)} U_t^{(i)} e^{j\phi_{k,t}^{(i)}}.$$

This allows us to extract recurring patterns of magnitude spectra that underlie observed complex spectra and the phase estimates of constituent signals. An efficient iterative algorithm is derived, which reduces under a particular condition to the multiplicative update

algorithm for non-negative matrix factorization (NMF) developed by Lee et al.

Even though the terms "complex" and "non-negative" may seem to conflict with each other and the decomposition is no longer a matrix factorization, we named this framework "Complex NMF", because it shares with NMF the ability to generate non-negative matrices H and  $U_{i}$ , while the input matrix Y is assumed to be a complex matrix and the algorithm also generates a third-rank complex-valued tensor  $Z_{k,t}^{i} = e^{j\phi_{k,t}^{(i)}}$ .

## 1. Introduction

### Sparse representation

Given a set of observed vectors  $y_1, \cdots, y_T$ , the goal is to find a set of basis vectors  $h_1, \dots, h_I$  such that any observations can be succinctly represented as a linear combination of a small number of "active" bases.

## 2. Research objective

Develop new framework that concurrently offers advantages of NMF-based and Sparse coding/Semi-NMF\*-based acoustic modeling

\* Semi-NMF (Ding et al., 2006)

Allows to project all signals that have the same spectral

variety of acoustic

phenomena with



# 3. Complex NMF (model)

### Model

 $|a_{k,t}^{(i)}\rangle$ 

Assume that the short-term Fourier transform (STFT) of an acoustic signal is composed of *I* complex-valued elements:

Each constituent,  $a_{k,t}^{(i)}$ , is assumed to have a magnitude spectrum which is constant up to the gain over time:

$$|a_{k,t}^{(i)}| = H_k^{(i)} U_t^{(i)} \quad (\forall_{k,i} H_k^{(i)} \ge 0, \forall_{i,t} U_t^{(i)} \ge 0),$$
  
Gain at frame  $t$   
Normalized magnitude  
spectrum template:  $\forall_i \sum_k H_k^{(i)} = 1$ 

and a time-varying phase spectrum:

## Objective function

Given a set of observations  $Y = \{Y_{k,t} | 1 \le k \le K, 1 \le t \le T\}$ , the goal is to find the optimal estimate of  $\theta = \{H_k^{(i)}, U_t^{(i)}, \phi_{k,t}^{(i)} | 1 \le k \le K, 1 \le t \le T, 1 \le i \le I\}.$ 

#### (1) Model reconstruction accuracy

Generative model:  $Y_{k,t} = F_{k,t} + \epsilon_{k,t}$  where  $\epsilon_{k,t} \sim \mathcal{N}_{\mathbb{C}}(0,\sigma^2)$ ( $\epsilon_{k,t}$  and  $\epsilon_{k',t'}$  are independent if  $(k,t) \neq (k',t')$ )

$$P(Y|\theta) = \prod_{k,t} \frac{1}{\pi\sigma^2} \exp\left(-\frac{|Y_{k,t} - F_{k,t}|^2}{\sigma^2}\right) \quad \text{(likelihood)}$$

#### (2) Sparsity of basis activations

As we want to achieve as parsimonious a representation as possible, we would like the  $U_{t}^{(i)}$ 's to be sparse.

This basically means that any observed complex spectrum should be well represented using only a few active magnitude spectrum bases each of which is paired with an arbitrary phase spectrum.





Generalized Gaussian distribution (GGD)

 $\rightarrow$  promotes sparsity when 0 andthe norm of H is bounded

MAP (Maximum A Posteriori) estimation problem leads to...

minimize 
$$f(\theta) \equiv \sum_{k,t} |Y_{k,t} - F_{k,t}|^2 + 2\lambda \sum_{i,t} |U_{i,t}|^p$$
  
subject to  $\sum_k H_k^{(i)} = 1 \quad (i = 1, \cdots, I)$ 

## 4. Complex NMF (algorithm)

Utilizing auxiliary function concept

#### **Definition**.

 $G^+(\theta, \theta)$  is an *auxiliary function* of the objective function  $G(\theta)$ if it satisfies  $G(\theta) = \min_{\bar{\theta}} G^+(\theta, \bar{\theta})$ .

#### **Theorem 1** (Auxiliary function method).

 $G(\theta)$  is non-increasing under the updates  $\theta \leftarrow \operatorname{argmin} G^+(\theta, \overline{\theta})$ and  $\bar{\theta} \leftarrow \operatorname{argmin} G^+(\theta, \bar{\theta}).$ 

#### Proof

Assume that we set  $\theta$  at an arbitrary value  $\theta_{\ell}$ . Let  $\theta_{\ell+1} = \operatorname{argmin}_{\bar{\theta}} G^+(\theta_{\ell}, \theta)$  and  $\theta_{\ell+1} = \operatorname{argmin}_{\theta} G^+(\theta, \bar{\theta}_{\ell+1})$ . It is obvious that  $G(\theta_{\ell}) = G^+(\theta_{\ell}, \overline{\theta_{\ell+1}})$ . We deduce from  $\theta_{\ell+1} = \operatorname{argmin}_{\theta} G^+(\theta, \overline{\theta}_{\ell+1})$  that  $G^+(\theta_{\ell}, \overline{\theta}_{\ell+1}) \geq$  $G^+(\theta_{\ell+1}, \bar{\theta}_{\ell+1})$ . By definition, from  $G^+(\theta_{\ell+1}, \bar{\theta}_{\ell+1}) \geq 0$  $G(\theta_{\ell+1})$  we verify that  $G(\theta_{\ell}) \geq G(\theta_{\ell+1})$ .

**Theorem 2** (Auxiliary function for Complex NMF).

 $f^{+}(\theta,\bar{\theta}) \equiv \sum \sum \frac{1}{Q_{k,t}} \left| \bar{Y}_{k,t}^{(i)} - H_{k}^{(i)} U_{t}^{(i)} e^{j\phi_{k,t}^{(i)}} \right|^{2}$ 



Condition for equivalence to NMF with Frobenius norm criterion We assume a particular situation:  $\forall_i e^{j\phi_{k,t}^{(i)}} = \frac{Y_{k,t}}{|Y_{k,t}|}$ .

$$\begin{split} \overline{k,t} &= i \quad \beta_{k,t} \\ + \lambda \sum_{t} \sum_{i} \left\{ p | \overline{U}_{t}^{(i)} |^{p-2} U_{t}^{(i)2} + (2-p) | \overline{U}_{t}^{(i)} |^{p} \right\}, \\ \text{with } \overline{\theta} &= \{ \overline{Y}_{k,t}^{(i)}, \overline{U}_{t}^{(i)} | \ 1 \le k \le K, 1 \le t \le T, 1 \le i \le I \}, \text{ is an} \\ \text{auxiliary function for } f(\theta), \text{ if} \\ \forall_{k,t} \sum_{i} \overline{Y}_{k,t}^{(i)} &= Y_{k,t}, \forall_{k,t} \sum_{i} \beta_{k,t}^{(i)} = 1, \forall_{i,k,t} \beta_{k,t}^{(i)} \in (0,1), p \in (0,2]. \end{split}$$

#### Proof

(1) By differentiating the Lagrangian  $\sum_{i} \frac{1}{\beta_{k,t}^{(i)}} \left| \bar{Y}_{k,t}^{(i)} - H_k^{(i)} U_t^{(i)} e^{j\phi_{k,t}^{(i)}} \right|^2 + \gamma \left( \sum_{i} \bar{Y}_{k,t}^{(i)} - Y_{k,t} \right)$ partially w.r.t.  $\bar{Y}_{k,t}^{(i)}$  and setting it at zero, we determine the minimum value  $|Y_{k,t} - F_{k,t}|^2$ . (2)  $p|\bar{U}|^{p-2}U^2 + (2-p)|\bar{U}|^p$  amounts to a convex quadratic function that is tangent to  $|U|^p$  at argument  $U = \pm \overline{U}$ .



0.5

### 5. Experiments

Conditions

**Activations** 

#### Convergence of Complex NMF algorithm

#### Speech data: excerpted from ATR B-set speech database, monaural and sampled at 16kHz

STFT was computed using Hanning window that was 32ms long with 16ms overlap.

H

• 
$$p = 1.2, \ \lambda = \sum_{k,t} |Y_{k,t}|^2 / I^{1-p/2} \times 10^{-5}$$
  
• Iteration #: 30

#### Initialization: random

I = 30

The aim of the experiments was to determine whether Complex NMF has, similarly to NMF, the effect of extracting recurring spectral patterns underlying the observed audio data.





#### objective function - reconstruction error sparseness 10 25 Iteration #

#### How did we obtain the separate signals?

The magnitude spectrum atom closest to the true spectrum was selected for each frame, and the framewise signals, each of which we constructed using the selected atom and the corresponding activation coefficient and phase spectrum, were concatenated to synthesize the whole signal stream.



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