Finite-time convergence is achieved by averaging

computational/communic

ation overheads on the central server are heavy.

Finite-time convergence is

achieved by iteratively averaging models across node pairs.

However, it can be achieved only

Node #4

 x_4

 $x_3 + x_4$

2

 $x_1 + x_2 + x_3 + x_4$

when the number of nodes n is

a power of 2.

 x_3

 $\frac{x_3 + x_4}{x_3 + x_4}$

2

 $x_1 + x_2 + x_3 + x_4$

Node

models from n nodes. However, when n is large,

Abstract

Decentralized learning is a fundamental technology to efficiently train machine learning models from a large amount of data by using computing nodes connected over a network (graph). Our proposed Base (k+1) graph guarantees finite-time convergence with any number of nodes and maximum number of connections (degree), enabling fast and stable decentralized learning. We evaluated the efficiency of the graph in a situation where each node has a statistically heterogeneous data subset, and confirmed that it can achieve fast and stable learning of models. This technology, which satisfies finite-time convergence while minimizing the number of operations and communications, will lead to reduce the entire power consumption of data centers.

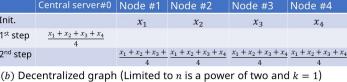
2

Goal and related studies

- P Goal: To learn collective intelligence models (e.g., image recognition models) by efficiently using computational resource and data on distributed data centers.
- Finite-time convergent graph: In NW with *n* nodes of degree k (maximum number of connections per a node), it is sufficient to design a graph in which each node can obtain average model of the local model $\{x_1, x_2, ..., x_n\}$ as $\bar{x} = (x_1 + \dots + x_n)/n$ through communication and operations

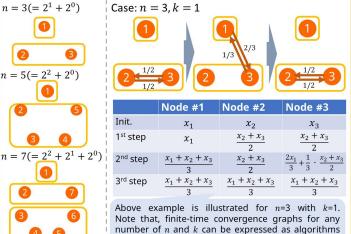
(weighted addition).

(a) Centralized graph (Any number of n) 0

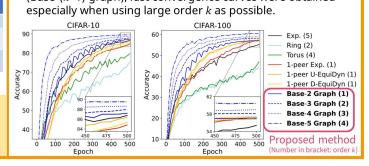


Proposed method and experiments

- A finite-time convergence graph (Base-(*k*+1) graph) that can >
- handle any number of nodes n and degree k is proposed [1]. Main Idea: Decompose *n* nodes into subsets consisting of a power of 2 nodes (see bottom left figure). Finite-time convergence is achieved by iteratively averaging within subsets and exchanging temporary models between subsets (see bottom right figure).



(source code is given in [2]). Decentralized learning of image recognition models in a situation where *n*=25 nodes hold statistically heterogeneous image data subsets was performed. By using proposed graph (Base-(k+1) graph), fast convergence curves were obtained



References

Node #1

2nd step $x_1 + x_2 + x_3 + x_4$

 x_1

 $x_1 + x_2$

Init.

Init.

1st step

1st step

2nd step

[1] Y. Takezawa, R. Sato, H. Bao, K. Niwa, and M. Yamada, "Beyond exponential graph: communication-efficient topologies for decentralized learning via finite-time convergence", in Proc. The Thirty-seventh Annual Conference on Neural Information Processing Systems (NeurIPS2023), 2023.

[2] https://github.com/yukiTakezawa/BaseGraph

(c) Decentralized graph (Any number of n, k)

with any number of degree k is essential.

Node #2

 x_2

 $x_1 + x_2$

2

 $x_1 + x_2 + x_3 + x_4$

There is no decentralized graph that achieves finite-time convergence for

interconnecting over multiple data centers for a model training, designing

finite-time convergent graphs that can handle a large number of nodes n

any *n* and *k*. For efficiently using a large number of computation nodes

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