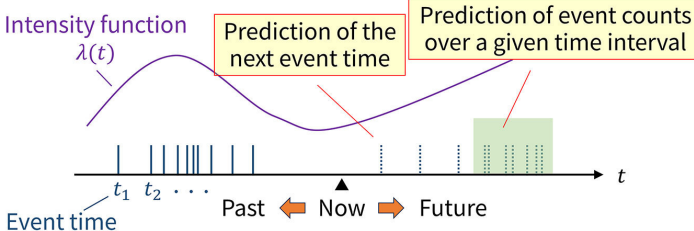


Abstract

If the timing of future events can be predicted, risks can be mitigated through proactive preparation, or opportunities can be fully leveraged. In this study, **we present a method for efficiently predicting future event times** by leveraging point processes and machine learning. While existing approaches achieve high predictive accuracy, they often require substantial computational cost during training. To address this issue, we replace the conventional log-likelihood objective with the least squares contrast for point processes, **enabling up to several hundred-fold speedups in training while maintaining comparable predictive performance**. This improvement makes our method scalable to large datasets. As machine learning-based event prediction becomes increasingly accurate with the growing volume of data, the associated computational burden also continues to rise. Our approach, which efficiently handles large-scale event series data, **aims to support proactive decision-making** by accurately predicting when events such as equipment failures or demand fluctuations will occur.

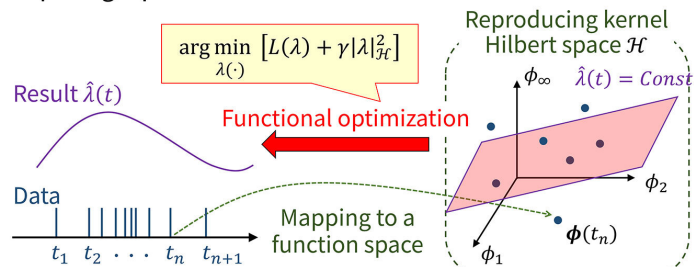
Event time series analysis

- Data that record **when and where events occur** are referred to as **event time series data**. e.g.) equipment failures, accidents, infections, SNS posts.
- Point processes provide a standard framework for analyzing such data. By learning **the intensity function** from data, they enable a wide range of analyses and predictions regarding the timing of future events.



Intensity function learning with kernel methods

Kernel methods are a class of machine learning techniques that enable flexible function learning from data without requiring a predefined functional form.



Challenge

For intensity function learning, the log-likelihood has been widely adopted as **the loss function** $L(\lambda)$ in kernel methods. However, this approach is **computationally expensive**, making it difficult to scale to large datasets.

Proposed method: Introducing least squares loss

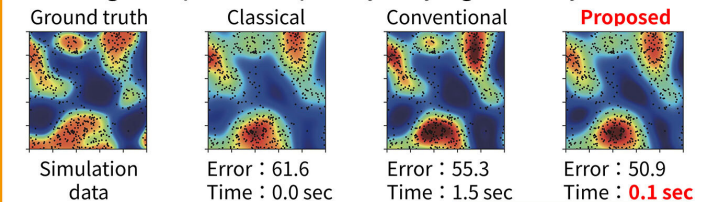
We propose fast kernel methods for estimating intensity functions that replaces the conventional log-likelihood objective with **the least squares loss for point processes**.

$$\text{Loss func.} \quad \begin{array}{l} \text{Negative log-likelihood} \\ \int_{\mathcal{T}} \lambda(t) dt - \sum_{n=1}^N \log(\lambda(t_n)) \end{array} \quad \begin{array}{l} \text{Least squares loss} \\ \int_{\mathcal{T}} \lambda(t)^2 dt - 2 \sum_{n=1}^N \lambda(t_n) \end{array}$$

Conventional methods require solving an optimization problem whose complexity can scale cubically with the size. In contrast, our method **eliminates the need for such costly optimization**, resulting in significant speedups.

■ Non-homogeneous Poisson processes [1]

Learning the spatio-temporally varying intensity function

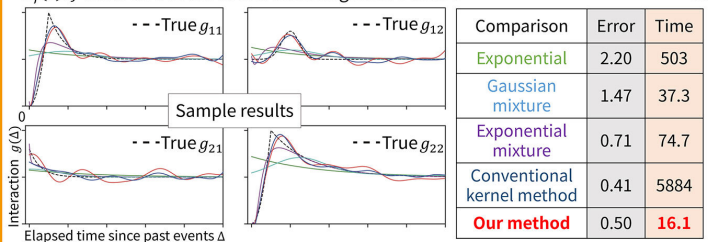


■ Hawkes processes [2]

Learning the interaction functions $g_{ij}(\Delta)$ governing dependencies among multiple event sequences.

$$\lambda_i(t) = \mu_i + \sum_{j \in \mathcal{U}} \int_{\mathcal{T}} g_{ij}(t-s) dN_j(s), \quad i \in \mathcal{U} := \{1, \dots, U\}$$

U : node number, μ_i : i -th node's base intensity, $N_j(s)$: j -th node's event count occurring before time s



References

- [1] H. Kim, T. Iwata, A. Fujino, "K2IE: Kernel method-based kernel intensity estimators for inhomogeneous Poisson processes," in *Proc. The 42nd International Conference on Machine Learning (ICML)*, 2025.
- [2] H. Kim, T. Iwata, "A representer theorem for Hawkes processes via penalized least squares minimization," in *Proc. The 14th International Conference on Learning Representations (ICLR)*, oral, 2026.

Contact

Hideaki Kim, Learning and Intelligent Systems Research Group, Innovative Communication Laboratory